

$\because \because \because \because \because O$
$1 \times 4$

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| $\begin{aligned} & y_{x} \\ & x_{x} \\ & x_{x} \end{aligned}$ | $\theta_{x_{11}}$ | ${ }_{\text {all }}{ }_{\text {x }}$ |  |
| :---: | :---: | :---: | :---: |
| $8_{0_{x 1}}^{8_{x+1}}$ |  | $8$ | $\begin{aligned} & d_{x_{2}} \\ & a_{0_{\text {maxx }}} \end{aligned}$ |
|  |  |  |  |



## User $C_{\text {reative }}$ Robot

